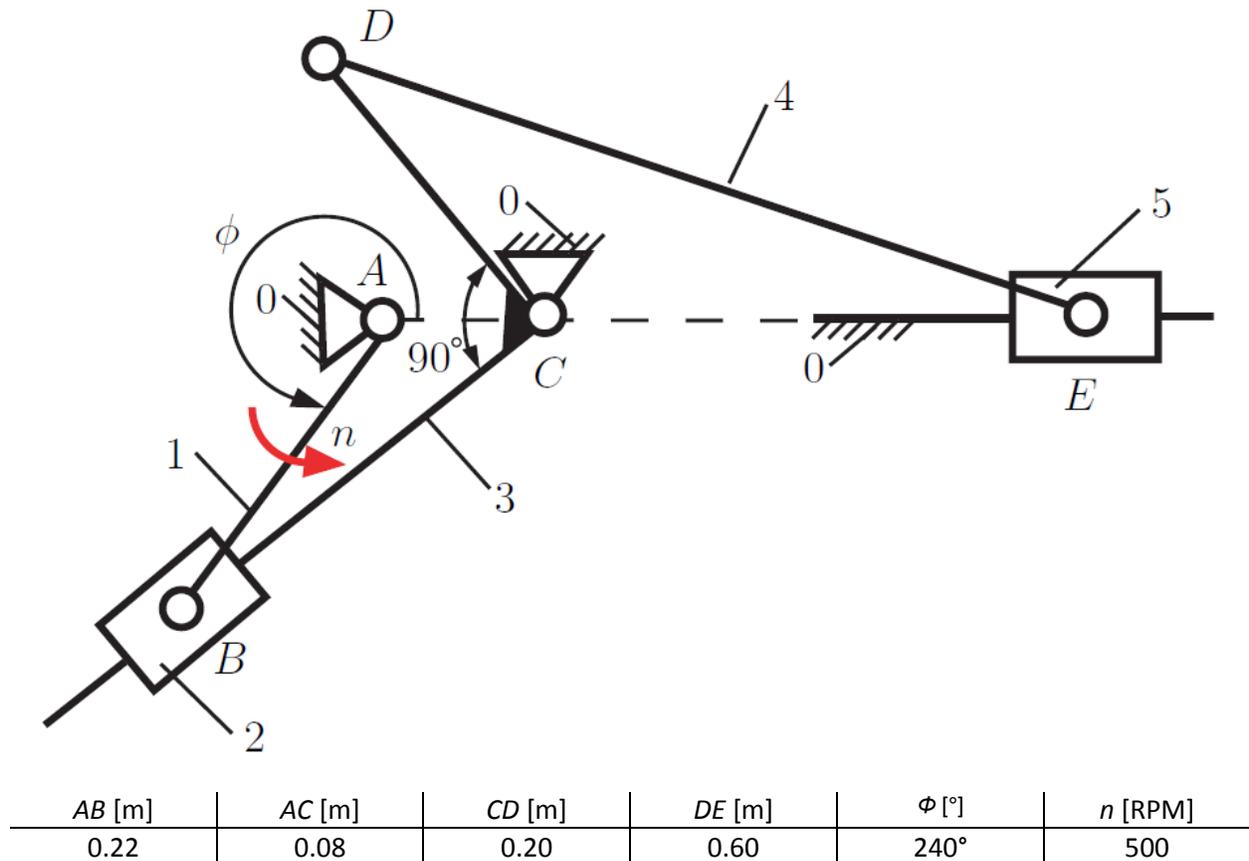


## Position Analysis

Ryan Brown – Mechanism 9, Index 1

Due 9/1/2015

## Mechanism Details



1. Find the positions of the joints and the angles of the links with the horizontal axis when the angle of the driver link 1 with the horizontal axis is  $\phi$ .

1. The position of A is considered the origin, so the position of joint A,  $\mathbf{A}=[0,0]$ .
2. The position of B is found using the following equation:

$$\begin{aligned}\mathbf{B} &= AB * \cos(\phi) * \bar{i} + AB * \sin(\phi) * \bar{j} \\ \mathbf{B} &= AB * \cos(240^\circ) * \bar{i} + AB * \sin(240^\circ) * \bar{j} \\ \mathbf{B} &= -.11 * \bar{i} - .1905 * \bar{j}\end{aligned}\tag{1}$$

3. C is located on the horizontal axis, so the y component of C is 0, and the position of C is  $\mathbf{C}=[.08,0]$ .

4. The angle of the link between B and C is found using the following equation:

$$\begin{aligned}\angle BC &= \arctan\left(\frac{y_C - y_B}{x_C - x_B}\right) \\ \angle BC &= \arctan\left(\frac{0 - (-.1905)}{.0800 - (-.1100)}\right) \\ \angle BC &= 45 \\ \angle BC &= 45.075 + 180 = 225.075^\circ\end{aligned}\quad (2)$$

5.  $\angle BC$  can be used to calculate  $\angle CD$  based off the fixed relationship

$$\begin{aligned}\angle CD &= \angle BC - 90^\circ \\ \angle CD &= 225.075^\circ - 90^\circ \\ \angle CD &= 135.075^\circ\end{aligned}\quad (3)$$

6. The position of joint D can be calculated using the following equation

$$\begin{aligned}\mathbf{D} &= CD * \cos(\angle CD) * \bar{i} + CD * \sin(\angle CD) * \bar{j} + \mathbf{C} \\ \mathbf{D} &= .20 * \cos(135.075^\circ) * \bar{i} + .20 * \sin(135.075^\circ) * \bar{j} + .08 * \bar{i} \\ \mathbf{D} &= -.0616 * \bar{i} + .1412 * \bar{j}\end{aligned}\quad (4)$$

7. The position of joint E can then be calculated using the Pythagorean Theorem:

$$\begin{aligned}(y_E - y_D)^2 + (x_E - x_D)^2 &= DE^2 \\ (0 - .1412)^2 + (x_E + .0616)^2 &= DE^2 \\ \mathbf{E} &= .5215 * \bar{i}\end{aligned}\quad (5)$$

8. Using the positions, along with equation 2, the rest of the angles with respect to the horizontal can be calculated.

The results of the above calculations give:

| Positions |        |        |
|-----------|--------|--------|
| Joint     | X      | Y      |
| A         | 0      | 0      |
| B         | -.1100 | -.1905 |
| C         | .0800  | 0      |
| D         | -.0616 | .1412  |
| E         | .5215  | 0      |

| Angles With Respect to (+) X-axis |          |
|-----------------------------------|----------|
| $\angle AB$                       | 240°     |
| $\angle BC$                       | 225.075° |
| $\angle CD$                       | 135.075° |
| $\angle DE$                       | 166.388° |